

This notebook is saved with all output deleted. To recreate all the calculations and the pictures go to the menu item

Evaluation-> Evaluate notebook ( the shortcut is Alt v + o )

To evaluate an individual cells use Shift+Enter

When you are done, before saving the notebook, delete all output by menu item Cell->Delete all output ( shortcut Alt c + l )

```
In[1]:= NotebookDirectory [ ]
```

```
Out[1]= C:\Dropbox\Work\myweb\Courses\Math_pages\Math_430\
```

```
In[2]:= NotebookFileName [ ]
```

```
Out[2]= C:\Dropbox\Work\myweb\Courses\Math_pages\Math_430\MoC_Burgers_eq1_v12.nb
```

---

## Burgers' Equation

The PDE

$$u(x, t) \frac{\partial u}{\partial x}(x, t) + \frac{\partial u}{\partial t}(x, t) = 0$$

is called *Burgers' equation*. This is NOT a linear equation. In this equation instead of the independent variable  $y$  we write  $t$  since it is convenient to think of it as time.

We will consider this equation subject to the initial condition

$$u(x, 0) = f(x) \text{ where } x \in \mathbb{R}. \text{ (To make illustrations in Mathematica we will choose } f(x) = \text{Exp}[-x^2].$$

The vector field that we need for the characteristic equations of this equation is  $\langle z, 1, 0 \rangle$ .

```
In[3]:= VPbe = {1.3`, -2.4`, 2.`}
```

```
Out[3]= {1.3, -2.4, 2.}
```

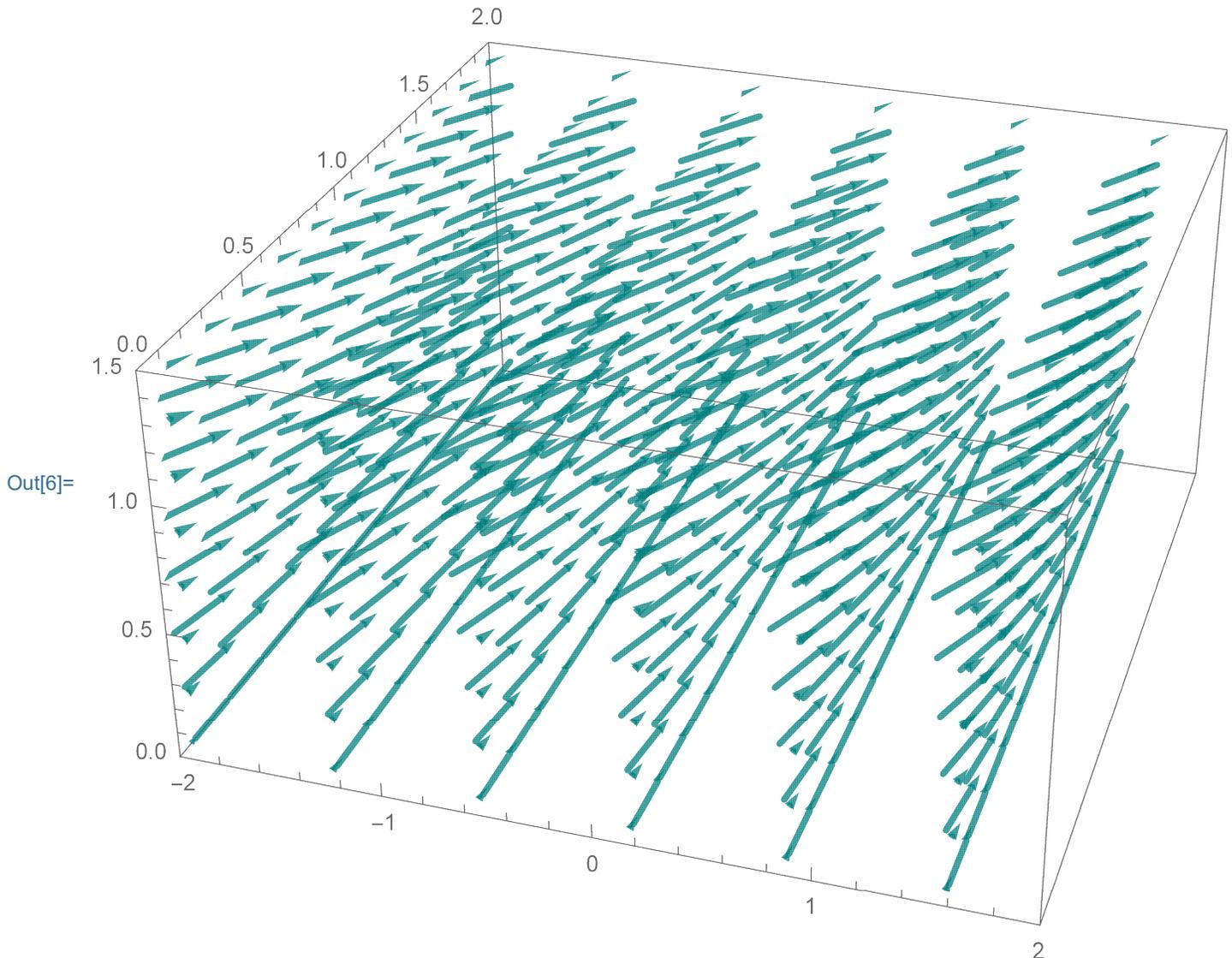
```
In[4]:= ChVecFiBE[{x_, t_, z_}] = {z, 1, 0}
```

```
Out[4]= {z, 1, 0}
```

2 | MoC\_Burgers\_eq1\_v12.nb  
In[5]:= VPbe = {0.8937514594363056`, -2.8253081061674683`, 1.6336592159871852` }

Out[5]= {0.893751, -2.82531, 1.63366}

```
In[6]:= vecsbe = VectorPlot3D[ChVecFiBE[{x, t, z}], {x, -2, 3}, {t, 0, 2},  
  {z, -0, 1.5},  
  VectorColorFunction -> (RGBColor[0, 0.5, 0.5] &),  
  VectorColorFunctionScaling -> False,  
  VectorStyle -> {Opacity[0.75], Thickness[0.006]},  
  VectorPoints -> {8, 12, 8}, VectorScale -> {0.07, Scaled[0.6]},  
  BoxRatios -> {2, 2, 1}, PlotRange -> {{-2, 2}, {0, 2}, {0, 1.5}},  
  ImageSize -> 500, ViewPoint -> Dynamic[VPbe]]
```



In[7]:= VPbe

Out[7]= {0.893751, -2.82531, 1.63366}

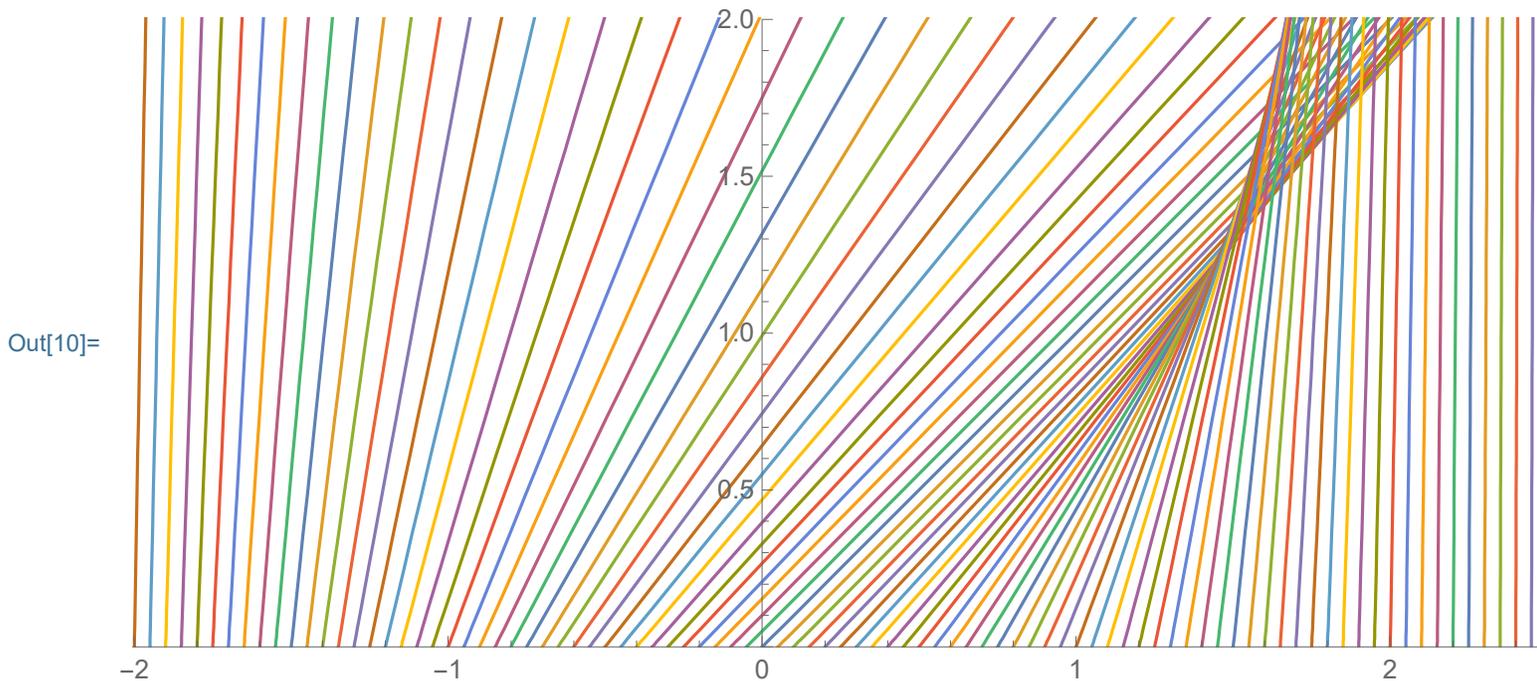
Now we need to solve the initial value problem for the **characteristic equations**. For that we will specify the initial condition for the Burgers' equation. We choose  $u[x,0] = \text{Exp}[-x^2]$ .

```
In[8]:= Clear[solbe];
solbe[s_, ξ_] =
  FullSimplify[{x[s], t[s], z[s]} /.
    DSolve[{x'[s] == z[s], t'[s] == 1, z'[s] == 0, x[0] == ξ, t[0] == 0,
      z[0] == Exp[-ξ²]}, {x[s], t[s], z[s]}, s][[1]]]
```

```
Out[9]= {e^{-ξ²} s + ξ, s, e^{-ξ²}}
```

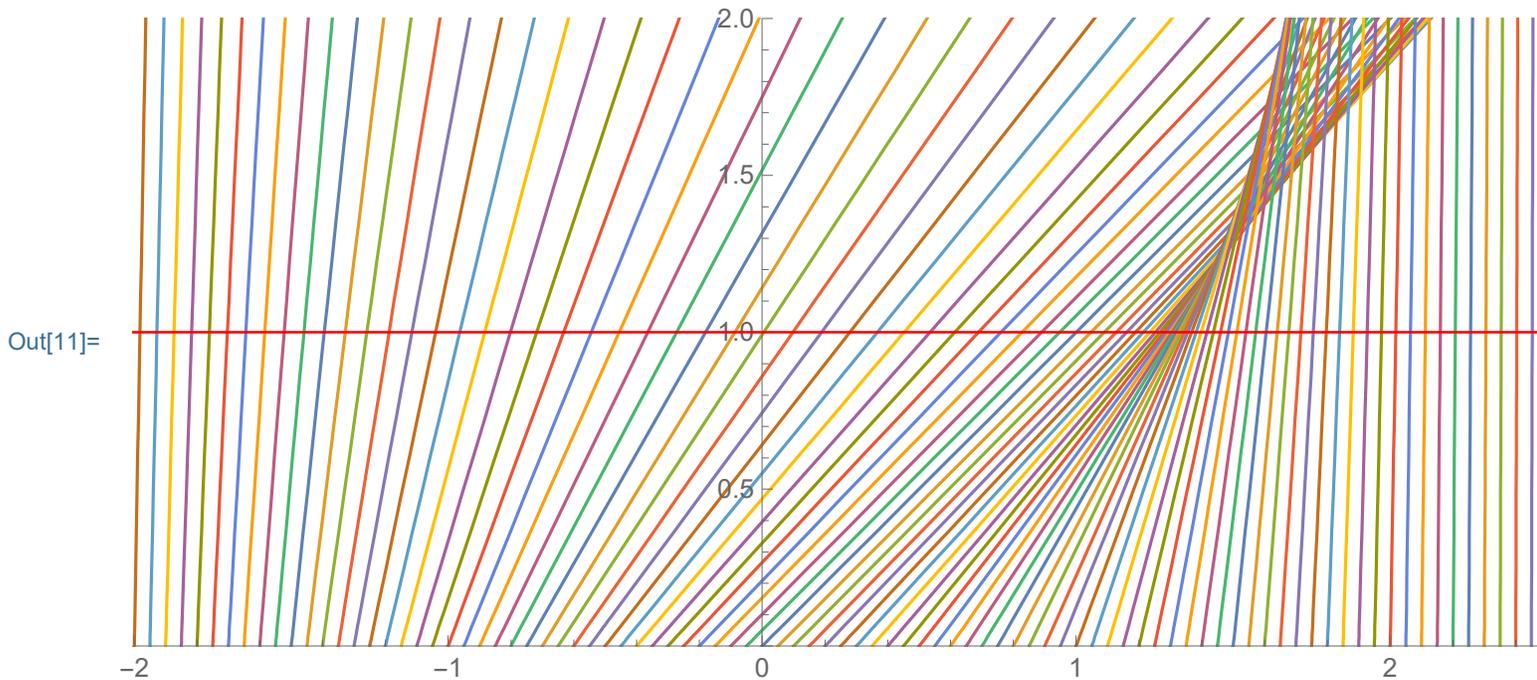
The above triple, for a fixed  $\xi$  and for a varying  $s$  gives a curve in  $xzt$ -space. For many  $\xi$ - $s$  we get many curves. These curves are the characteristics of Burgers' equation. However, for Burgers' equation the projected characteristics are more important. (Projected characteristics are the projections of the characteristics onto  $xt$ -plane.) Below we plot the projected characteristics. They are straight lines with slope  $\text{Exp}[-\xi^2]$  in the  $xt$ -plane.

```
In[10]:= ParametricPlot[Evaluate[Table[solbe[s, ξ][[1, 2]], {ξ, -9, 3, .05}],
  {s, 0, 6}, PlotStyle -> {Thickness[0.002]}, PlotRange -> {{-2, 3}, {0, 2}},
  ImageSize -> 600]
```



Recall that the value of  $z$  along a fixed projected characteristic is constant. Thus at the points where projected characteristics intersect the function  $u(x, t)$  should be having two different values. That is clearly impossible. Next we will try to answer the following question: What is the maximum time  $t_m$  for which no projected characteristics intersect below the line  $t = t_m$ . I will first guess that value, say  $t_m = 1$ .

```
In[11]:= ParametricPlot[Evaluate[Table[solbe[s,  $\xi$ ][[1, 2]], { $\xi$ , -9, 3, .05}]],
  {s, 0, 6}, PlotStyle -> {Thickness[0.002]},
  Epilog -> {{Red, Line[{{-3, 1}, {5, 1}}]}}, PlotRange -> {{-2, 3}, {0, 2}},
  ImageSize -> 600]
```



From this plot it is clear that  $t_m > 1$ . Next we will try to find the exact value of  $t_m$ .

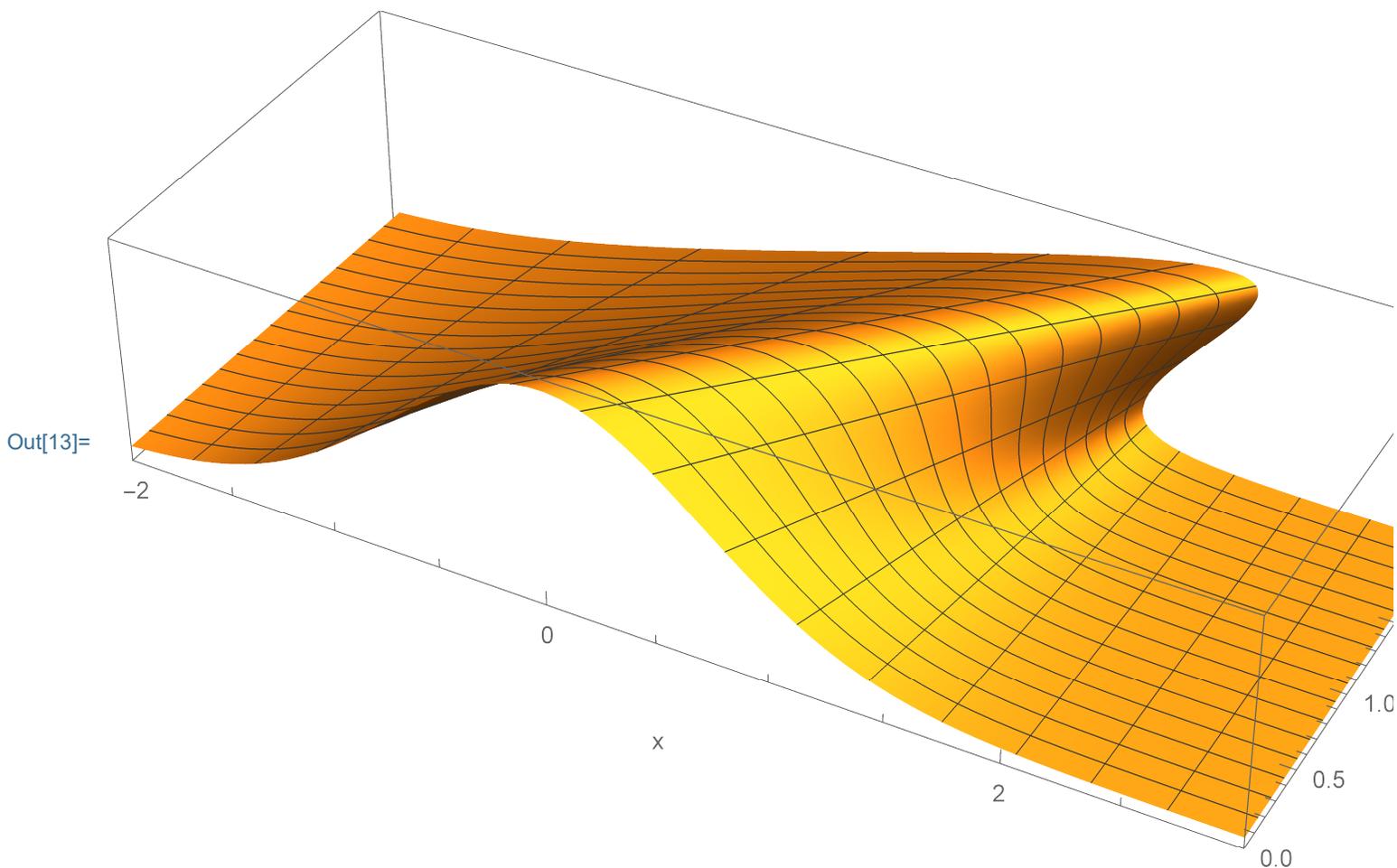
First look at the surface that we found.

```
In[12]:= solbe[s,  $\xi$ ]
```

```
Out[12]= { $e^{-\xi^2} s + \xi, s, e^{-\xi^2}$ }
```

This is a parametric equation of a surface in  $xzt$ -space.

```
In[13]:= ParametricPlot3D[solbe[s,  $\xi$ ], { $\xi$ , -2, 3}, {s, 0, 2}, PlotPoints  $\rightarrow$  {70, 30},
PlotRange  $\rightarrow$  {{-2, 3}, {0, 2}}, ImageSize  $\rightarrow$  600, AxesLabel  $\rightarrow$  {"x", "t", "z"}]
```



Think of a fixed time in the above plot, say  $t = t_0$ , and consider the curve  $z = u(x, t_0)$ . From the graph we can see that for small values of  $t_0$  we have that  $z = u(x, t_0)$  is a function. But for some larger values of  $t_0$ , say close to 2, we have that  $z = u(x, t_0)$  is NOT a function.

Recall the equation of this surface:

```
In[14]:= solbe[s,  $\xi$ ]
```

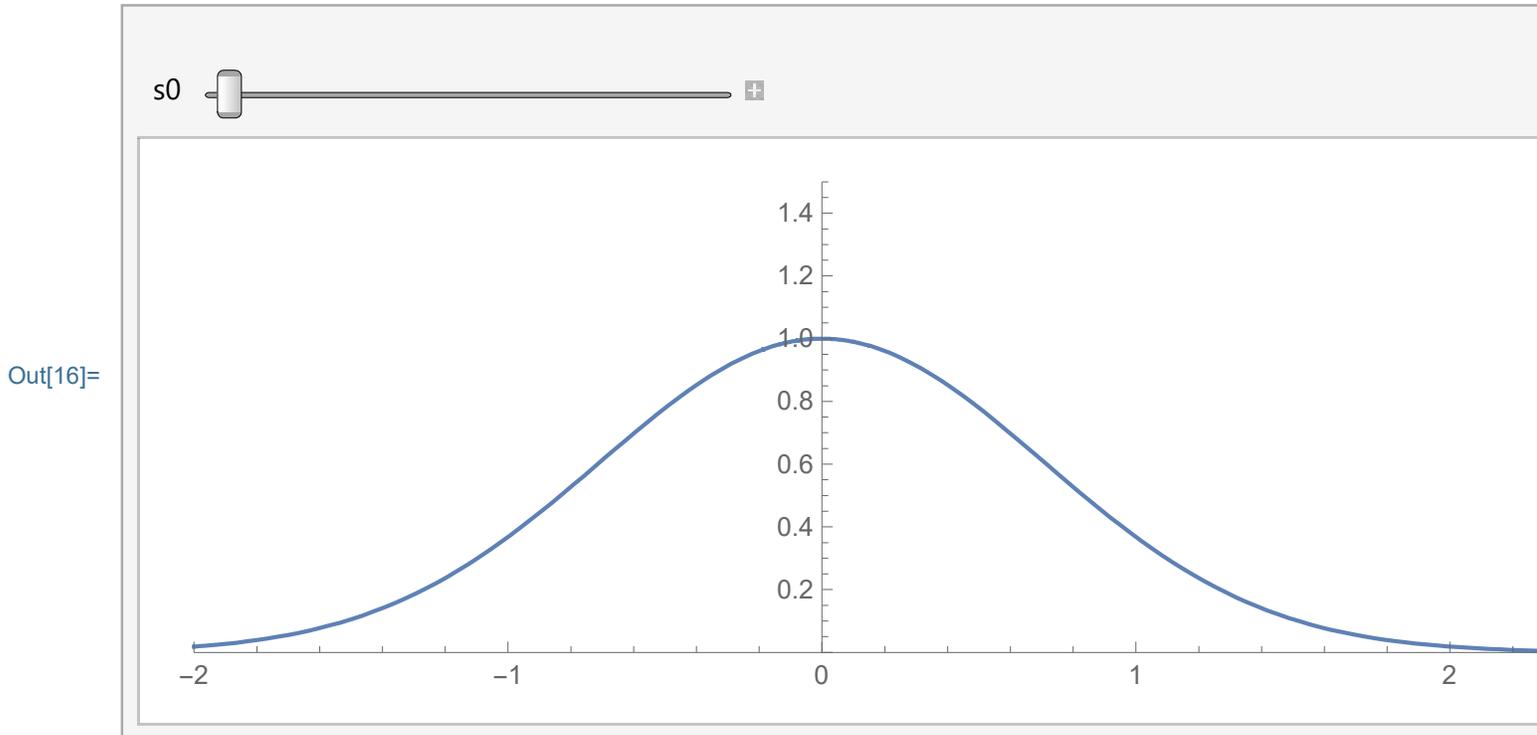
```
Out[14]= { $e^{-\xi^2} s + \xi, s, e^{-\xi^2}$ }
```

A lucky aspect of this equation is that the time is the second coordinate, that is the time equals  $s$ . Next I will explore the parametric curves with fixed  $s = s_0$

```
In[15]:= solbe[s0,  $\xi$ ]
```

```
Out[15]= { $e^{-\xi^2} s_0 + \xi, s_0, e^{-\xi^2}$ }
```

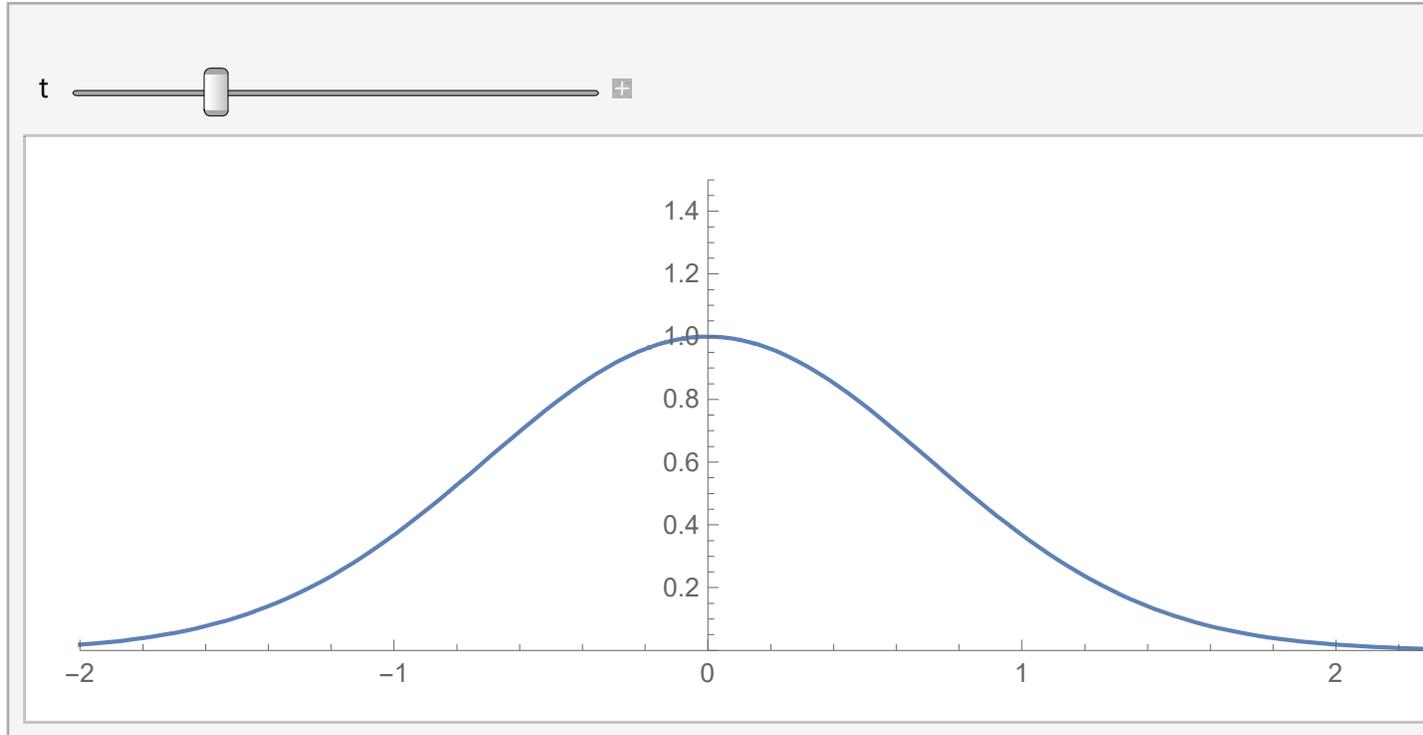
```
In[16]:= Manipulate[ParametricPlot[solbe[s0,  $\xi$ ][{1, 3}], { $\xi$ , -2, 3},  
PlotPoints  $\rightarrow$  150, PlotRange  $\rightarrow$  {{-2, 3}, {0, 1.5}}, ImageSize  $\rightarrow$  600],  
{s0, 0, 3}, ControlPlacement  $\rightarrow$  Top]
```



Since the parameter  $s$  is in fact the time, I will change the variable name to  $t$ . It does not make any difference mathematically but it might be easier to think about what is going on. I will also add some negative time to get the idea how this process evolves.

```
In[17]:= Manipulate[ParametricPlot[solbe[t,  $\xi$ ][{1, 3}], { $\xi$ , -2, 3},
  PlotPoints  $\rightarrow$  150, PlotRange  $\rightarrow$  {{-2, 3}, {0, 1.5}}, ImageSize  $\rightarrow$  600],
  {{t, 0}, -1, 3}, ControlPlacement  $\rightarrow$  Top]
```

Out[17]=



As I pointed out earlier from the above graphs we can see that for small values of  $t$  we have that  $z = u(x, t)$  is a function. But for some larger values of  $t$ , say close to 2, we have that  $z = u(z, t)$  is NOT a function. The point is to find the exact value of the cut-off  $t$ . To find that  $t$  I will add the tangent vector to the above parametric curve. Recall that  $t$  is fixed and  $\xi$  is the variable, so the tangent vector is

```
In[18]:= solbe[t,  $\xi$ ][{1, 3}]
```

```
Out[18]= { $e^{-\xi^2} t + \xi, e^{-\xi^2}$ }
```

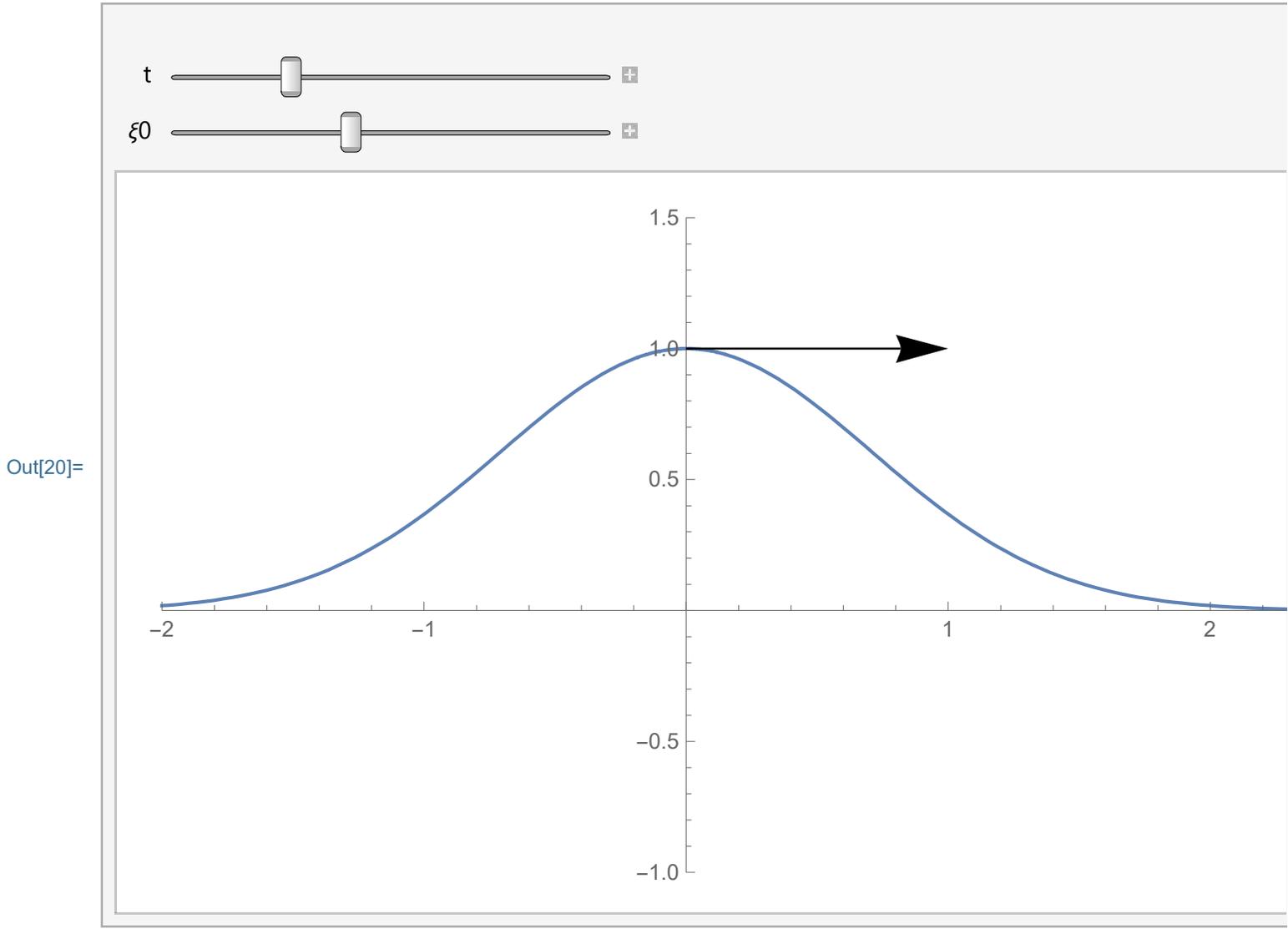
```
In[19]:= D[solbe[t,  $\xi$ ][{1, 3}],  $\xi$ ]
```

```
Out[19]= { $1 - 2 e^{-\xi^2} t \xi, -2 e^{-\xi^2} \xi$ }
```

```

In[20]:= Manipulate[ParametricPlot[solbe[t, ξ][[1, 3]], {ξ, -2, 3},
  PlotPoints → 150,
  Epilog →
  { {Arrow[{{e^{-ξ0^2} t + ξ0, e^{-ξ0^2}},
    {e^{-ξ0^2} t + ξ0, e^{-ξ0^2}} + {1 - 2 e^{-ξ0^2} t ξ0, -2 e^{-ξ0^2} ξ0}}]}],
  PlotRange → {{-2, 3}, {-1, 1.5}}, ImageSize → 600], {{t, 0}, -1, 3},
  {{ξ0, 0}, -2, 3}, ControlPlacement → Top]

```



Based on this manipulation, can you calculate the the value of  $t$  for which  $z = u(z, t)$  becomes multivalued?

Here is the calculation:

Calculate the tangent vector to the curve

In[21]:= `solbe[t,  $\xi$ ] [{1, 3}]`

Out[21]=  $\{e^{-\xi^2} t + \xi, e^{-\xi^2}\}$

for a fixed  $t$

In[22]:= `D[solbe[t,  $\xi$ ] [{1, 3}],  $\xi$ ]`

Out[22]=  $\{1 - 2 e^{-\xi^2} t \xi, -2 e^{-\xi^2} \xi\}$

The first component of the tangent vector is

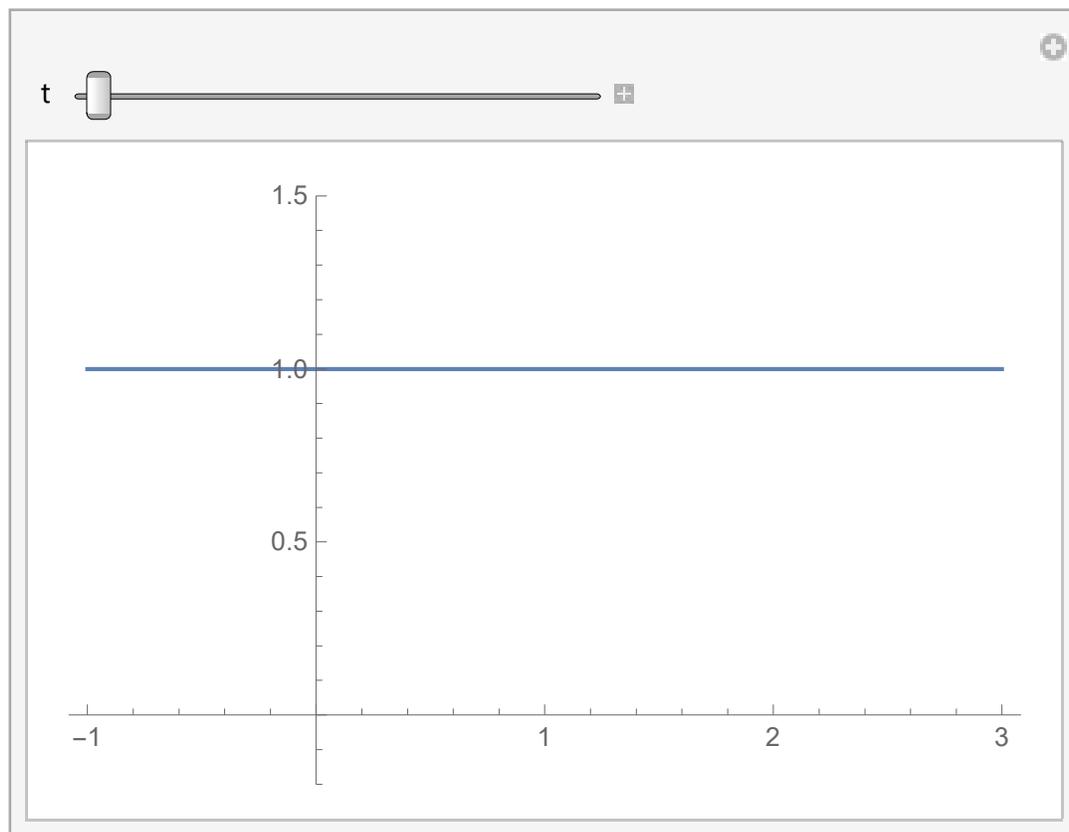
In[23]:= `D[solbe[t,  $\xi$ ] [{1, 3}],  $\xi$ ] [[1]]`

Out[23]=  $1 - 2 e^{-\xi^2} t \xi$

Plot this function for a fixed  $t$  and then manipulate  $t$ :

In[24]:= `Manipulate[Plot[ $1 - 2 e^{-\xi^2} t \xi$ , { $\xi$ , -1, 3}, PlotRange  $\rightarrow$  {-0.2, 1.5}], {t, 0, 2}, ControlPlacement  $\rightarrow$  Top]`

Out[24]=



Find the derivative of the first component of the tangent vector.

In[25]:= **FullSimplify**[**D**[ $1 - 2 e^{-\xi^2} t \xi$ ,  $\xi$ ]]

Out[25]=  $2 e^{-\xi^2} t (-1 + 2 \xi^2)$

Find for which  $\xi$  the function  $1 - 2 e^{-\xi^2} t \xi$  takes a minimum.

In[26]:= **Solve**[ $-2 e^{-\xi^2} t + 4 e^{-\xi^2} t \xi^2 == 0$ ,  $\xi$ ]

Out[26]=  $\left\{ \left\{ \xi \rightarrow -\frac{1}{\sqrt{2}} \right\}, \left\{ \xi \rightarrow \frac{1}{\sqrt{2}} \right\} \right\}$

Calculate the second derivative of the first component to prove that it reaches the minimum at the above value of  $\xi$ :

In[27]:= **FullSimplify**[**D**[ $1 - 2 e^{-\xi^2} t \xi$ ,  $\{\xi, 2\}$ ] /.  $\left\{ \xi \rightarrow \frac{1}{\sqrt{2}} \right\}$ ]

Out[27]=  $4 \sqrt{\frac{2}{e}} t$

Since  $t$  is positive, the last quantity is positive. Thus, the first component of the tangent vector has the minimum at  $\xi = \frac{1}{\sqrt{2}}$

In[28]:=  $(1 - 2 e^{-\xi^2} t \xi)$  /.  $\left\{ \xi \rightarrow \frac{1}{\sqrt{2}} \right\}$

Out[28]=  $1 - \sqrt{\frac{2}{e}} t$

Hence: at  $\xi = 1/\sqrt{2}$  the derivative of the first component of the tangent vector takes the minimum value  $1 - \sqrt{\frac{2}{e}} t$ . Finally, for which  $t$  is this minimum equal to 0:

In[29]:= **Solve**[ $1 - \sqrt{\frac{2}{e}} t == 0$ ,  $t$ ]

Out[29]=  $\left\{ \left\{ t \rightarrow \sqrt{\frac{e}{2}} \right\} \right\}$

In[30]:=  $N[\sqrt{E/2}]$

Out[30]= 1.16582

Thus, the parametric equations

In[31]:= `solbe[t,  $\xi$ ]`

Out[31]=  $\{e^{-\xi^2} t + \xi, t, e^{-\xi^2}\}$

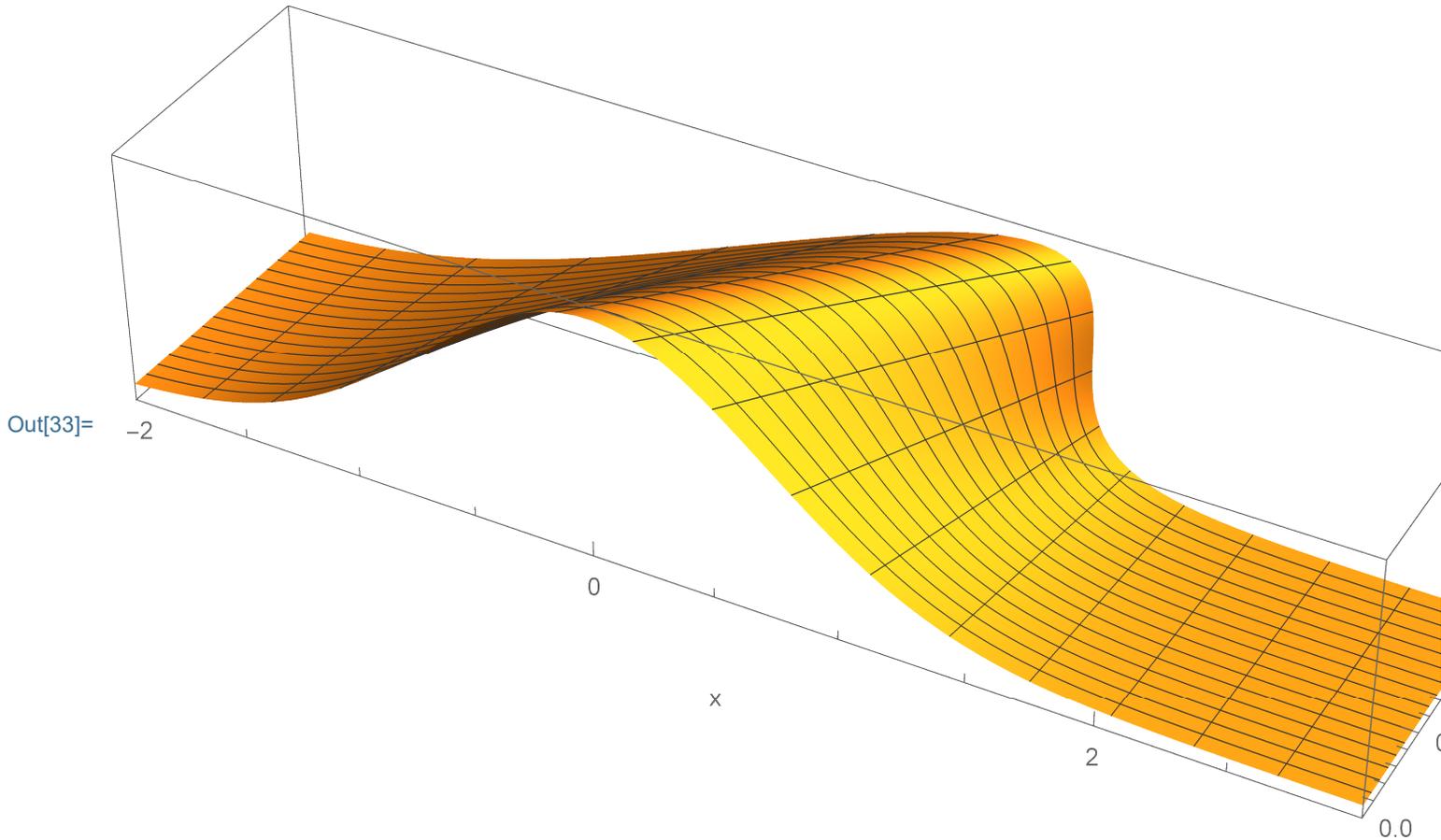
represent a function for all  $(t, \xi)$  such that  $t \in [0, \sqrt{e/2}]$  and  $\xi \in \mathbb{R}$ . Although we can not find an explicit formula for the function  $u(x, t)$ . For that formula we would need to solve

In[32]:= `Solve[Exp[- $\xi^2$ ] t +  $\xi$  == x,  $\xi$ ]`

 **Solve:** This system cannot be solved with the methods available to Solve.

Out[32]= `Solve[e- $\xi^2$  t +  $\xi$  == x,  $\xi$ ]`

```
In[33]:= ParametricPlot3D[solve[t,  $\xi$ ], { $\xi$ , -2, 3}, {t, 0,  $\sqrt{\frac{e}{2}}$ },
PlotPoints  $\rightarrow$  {70, 30}, PlotRange  $\rightarrow$  {{-2, 3}, {0,  $\sqrt{\frac{e}{2}}$ }}, ImageSize  $\rightarrow$  600,
AxesLabel  $\rightarrow$  {"x", "t", "z"}]
```



Mathematica algorithms can not solve this equation:

```
In[34]:= Clear[ff, u];
DSolve[{u[x, t]  $\times$  D[u[x, t], x] + D[u[x, t], t] == 0, u[x, 0] == ff[x]},
u[x, t], {x, t}]
```

```
Out[34]= DSolve[
{u(0,1)[x, t] + u[x, t] u(1,0)[x, t] == 0, u[x, 0] == ff[x]}, u[x, t], {x, t}]
```

Or, with the specific initial condition that we used:

In[35]:= `DSolve[{u[x, t] × D[u[x, t], x] + D[u[x, t], t] == 0, u[x, 0] == Exp[-x^2]}, u[x, t], {x, t}]`

 **Solve:** Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information.

Out[35]= `DSolve[{u(0,1)[x, t] + u[x, t] u(1,0)[x, t] == 0, u[x, 0] == e-x2}, u[x, t], {x, t}]`